



**NEW YORK UNIVERSITY**

Institute of Mathematical Sciences

Division of Electromagnetic Research

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# **An Infinite System of Linear Equations Arising in Diffraction Theory**

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Project Director

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Abstract

An infinite system of linear equations is investigated which arises in the theory of diffraction by a circular aperture. The coefficients of this system depend on a parameter  $\alpha$ . It is proved that the solution of the system can be found to any degree of approximation by solving the first  $N$  equations for the first  $N$  unknowns, for  $N$  sufficiently large, if  $\alpha$  is either real or purely imaginary.

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# 1. Introduction

We consider the problem of diffraction of a plane scalar wave normally incident on a plane screen with a circular aperture. Let  $u$  be the solution of

$$\Delta u + K^2 u = 0$$

which represents the diffracted wave and let  $\rho, \theta$  be polar coordinates on the screen such that  $\rho = 0$  represents the center of the aperture. We assume that on the screen  $u = 0$ . Let the radius of the aperture be  $a$  and let  $\Phi(\rho)$  be the value of  $u$  in the aperture,  $0 \leq \rho \leq a$ . Then the following result was derived by Bouwkamp<sup>[1]</sup> using the variational method of Levine and Schwinger<sup>[2]</sup>:

If  $\Phi(\rho)$  is expanded in a series of Legendre polynomials of the type

$$(1.1) \quad \Phi(\rho) = \sum_{n=0}^{\infty} b_n P_{2n+1} \left( \sqrt{1-\rho^2/a^2} \right)$$

then the  $b_n$  satisfy the system of infinitely many linear equations

$$(1.2) \quad \sum_{n=0}^{\infty} d_{m,n} b_n = \frac{6}{ia} \delta_{m,0},$$

where  $\alpha = Ka$ ,  $\delta_{0,0} = 1$  and  $\delta_{m,0} = 0$  if  $m \neq 0$ , and where

$$(1.3) \quad d_{m,n} = \left( \frac{6}{\alpha} \right)^2 \frac{\Gamma(n+3/2)}{n!} \frac{\Gamma(m+3/2)}{m!} g_{m,n}^*(\alpha)$$

and

$$(1.4) \quad g_{m,n}^*(\alpha) = \int_0^{\infty} \frac{\sqrt{v^2-1}}{v^2} J_{2m+3/2}(\alpha, v) J_{2n+3/2}(\alpha v) dv.$$

In Eq. (1.4),  $J$  denotes the Bessel function of the first kind, and

$$(1.5) \quad \sqrt{v^2-1} = -i \sqrt{1-v^2}, \quad \sqrt{1-v^2} > 0$$

for  $0 \leq v < 1$ . The diffracted amplitude at infinity in the forward direction is given by

$$(1.6) \quad A_1 = -\frac{ia}{3} b_0.$$

The occurrence of an infinite system of linear equations is typical for the variational method. The system (1.2) has the advantage that its matrix reduces to a diagonal matrix if  $\alpha \rightarrow 0$  (see Eq. (2.9) below). It has other advantages for  $\alpha \rightarrow \infty$ : it can be shown that the limit

$$\lim_{\alpha \rightarrow \infty} \alpha^{-1} g_{m,n}^*(\alpha) = g_{m,n}^{(\infty)}$$

exists and that the infinite matrix with the general element  $g_{m,n}^{(\infty)}$  has a formal inverse. But we shall not use this fact here.

The main purpose of the present report is to establish that Bouwkamp's system (1.2) of infinitely many linear equations can be used effectively for the purpose of computing the field in the aperture and the transmission coefficient  $A_1$  of (1.6). It is shown that this can be done approximately for all real values of  $\alpha$  by solving the first  $N+1$  equations (1.2) for the first  $N+1$  unknowns (assuming that the remaining unknowns have the value zero). For sufficiently small values of  $|\alpha|$ , this has already been proved for Levine and Schwinger's system of linear equations in an earlier report [3]. The present approach also gives some general insight into the dependency of the unknowns  $b_n$  on the parameter  $\alpha$ ; in particular, we show that the  $b_m$  are analytic functions of the complex variable  $\alpha$  which do not have any singularities on the imaginary  $\alpha$ -axis (see Theorem I).



## 2. A Fredholm integral equation equivalent to Bouwkamp's system of linear equations

Instead of Bouwkamp's coefficients  $b_n$  for the expansion of the field in the aperture we now introduce the quantities

$$(2.1) \quad s_n = (-1)^n \frac{\Gamma(n+3/2)}{n!} b_n$$

and consider the system of linear equations

$$(2.2) \quad \sum_{n=0}^{\infty} g_{m,n} s_n = t_m \quad (n, m = 0, 1, 2, \dots),$$

where

$$(2.3) \quad g_{n,m} = g_{n,m}(\alpha) = (-1)^{n+m} \int_0^{\infty} \frac{\sqrt{v^2-1}}{v} J_{2m+3/2}(\alpha v) J_{2n+3/2}(\alpha v) \frac{dv}{v}.$$

If we put  $\delta_{m,n} = 0$  ( $m \neq n$ ),  $\delta_{n,n} = 1$ , and define

$$(2.4) \quad t_m = -\frac{i\alpha}{6} \frac{m!(-1)^m}{\Gamma(m+3/2)} \delta_{m,0},$$

then the system (2.2) is the equivalent of Bouwkamp's system for the new unknowns  $s_n$  and the new right-hand sides  $t_m$ . The conditions for the  $b_n$  imply the following conditions for the  $s_n$ : first, that

$$(2.5) \quad \lim_{\epsilon \rightarrow 0} \sum_0^{\infty} \frac{(-1)^n n!}{\Gamma(n+3/2)} s_n P_{2n+1}^{(1-\epsilon)}$$

exists, and second, that

$$(2.6) \quad \sum_{n=0}^{\infty} \left| \frac{s_n}{n+\frac{1}{2}} \right|^2 < \infty$$

Condition (2.6) can be derived from the fact that the field in the aperture must be square integrable and from the equation

$$\lim_{n \rightarrow \infty} \frac{\Gamma(n+3/2)}{n! \sqrt{n+1/2}} = 1.$$

We shall now investigate the system (2.2) under the assumption that

$$(2.7) \quad \sum_{m=0}^{\infty} (4m+3) |t_m| < \infty,$$

which is obviously justified for the particular values of the  $t_m$  in (2.4).

For this purpose we need the following

Lemma 1. Let

$$(2.8) \quad G \equiv G(s, \sigma, \alpha) = \int_0^{\infty} \frac{\sqrt{v^2-1} - v}{v} \sin(\alpha v s) \sin(\alpha v \sigma) dv,$$

where

$$\sqrt{v^2-1} = -i \sqrt{1-v^2} \quad \text{for} \quad 0 \leq v \leq 1.$$

Then

$$(2.9) \quad \int_0^1 \int_0^1 G(s, \sigma, \alpha) P_{2n+1}(s) P_{2m+1}(\sigma) ds d\sigma \\ = \frac{\pi}{2\alpha} \left[ g_{m,n}(\alpha) - \delta_{m,n}/(4n+3) \right].$$

Proof: From the 'degenerate' addition theorem for Bessel functions [see [6], p. 102] we have

$$(2.10) \quad \sin(\alpha v s) = [\pi/(2\alpha)]^{1/2} \sum_{m=0}^{\infty} (-1)^m (4m+3) J_{2m+3/2}(\alpha v) P_{2m+1}(s).$$

The series in (2.10) converges absolutely and uniformly for all real values of  $\alpha$ ,  $v$  and  $s$  if  $0 \leq s \leq 1$ .

By substituting the right-hand side of (2.10) for  $\sin(\alpha v s)$  [and the corresponding expression for  $\sin(\alpha v \sigma)$ ] in the right-hand side of (2.8) we find

$$(2.11) \quad G = \frac{\pi}{2\alpha} \int_0^\infty \frac{\sqrt{v^2-1}-v}{v^2} dv \sum_{m,n=0}^\infty (-1)^{n+m} (l_{m+3})(l_{n+3}) J_{2m+3/2}(\alpha v) J_{2n+3/2}(\alpha v) \\ \cdot P_{2m+1}(s) P_{2n+1}(\sigma) .$$

Now we can derive (2.9), with the  $g_{n,m}$  as defined in (2.3), from (2.11); for this we use the orthogonality relations

$$(2.12) \quad \int_0^1 P_{2m+1}(s) P_{2n+1}(s) ds = \frac{\delta_{m,n}}{l_{m+3}} ,$$

and the following special case of the Sonine-Schafheitlin integral (see [6], p. 51):

$$(2.13) \quad \int_0^\infty J_{2m+3/2}(\alpha v) J_{2n+3/2}(\alpha v) \frac{dv}{v} = \frac{\delta_{m,n}}{l_{m+3}} .$$

This derivation of (2.9) requires exchanging the order of summation and integration in (2.11), which is easily justified.

Lemma 1 leads immediately to an integral equation of the second kind whose kernel is  $\frac{2\alpha}{\pi} G(s, \sigma, \alpha)$ ; this equation is equivalent to the system (2.2). Indeed, if we introduce the functions

$$(2.14) \quad S(\sigma) = \sum_{n=0}^\infty s_n P_{2n+1}(\sigma),$$

$$(2.15) \quad T(s) = \sum_{m=0}^\infty t_m P_{2m+1}(s),$$

then Eqs. (2.9), (2.2) and (2.12) immediately give the result

$$(2.16) \quad T(s) = S(s) + \frac{2a}{\pi} \int_0^1 G(s, \sigma; a) S(\sigma) d\sigma.$$

It is easy to see that any continuous solution  $S(s)$  of (2.16) leads, via (2.14), (2.15) and (2.9), to a solution of (2.2) satisfying (2.5) and (2.6). This is due to the fact that  $G(s, \sigma, a)$  can be expanded in a power series in  $s + \sigma$  and  $|s - \sigma|$  which is everywhere convergent, (see (3.2), (3.3) below). Therefore, the integral on the right-hand side of (2.16) satisfies a Lipschitz condition if  $S(\sigma)$  is continuous. From this it follows that  $S(s) - T(s)$  can be expanded in a series of type (2.15) satisfying (2.5) and (2.6), and from (2.7) the same follows for  $S(s)$  itself.

It is more difficult to show that every admissible solution of (2.2) leads to a solution  $S(s)$  of (2.16). We can omit a discussion of this problem because we shall prove later that (2.16) has a continuous solution  $S(\sigma)$  for all finite real positive values of  $a$ . Therefore, we always have an admissible solution of (2.2), and it follows from well-known uniqueness theorems (Bouwkamp<sup>[4]</sup>, Meixner<sup>[5]</sup>) that there cannot be a second such solution. Finally, we shall prove that the solution  $S(\sigma)$  obtained from (2.16) could also be derived from (2.2) by solving the  $N$  first equations for the  $N$  first unknowns in (2.2) and letting  $N \rightarrow \infty$  (see Section 5).

### 3. Various forms of the kernel $G(s, \sigma, a)$

For a detailed study of the integral equation (2.16) we need various forms of the kernel  $G$ . We have:

Lemma 2. The kernel  $G(s, \sigma, a)$  can be defined for all complex values of  $a$  and for all real values of  $s, \sigma$  by

$$(3.1) \quad G(s, \sigma; a) = \int_0^{\infty} \left( \sqrt{v^2 - 1} - v \right) \sin(av s) \sin(av \sigma) \frac{dv}{v}$$

$$(3.2) \quad = -\frac{i}{2} \int_0^1 \sqrt{1-w^2} \left\{ e^{iaw|s-\sigma|} - e^{iaw(s+\sigma)} \right\} \frac{dw}{w}$$

$$(3.3) \quad = -\frac{\pi}{4} \int_{|s-\sigma|}^{|s+\sigma|} \left\{ J_1(a\tau) + iH_1(a\tau) \right\} \frac{d\tau}{\tau},$$

where  $J_1$  denotes the Bessel function of the first kind and  $H_1$  denotes the Struve function, both of order one. Eqs. (3.2) and (3.3) provide formulas for the analytic continuation of  $G(s, \sigma; a)$  into the complex  $a$ -plane.

Proof: We shall derive (3.2) for  $s \geq \sigma$ , that is, for  $|s-\sigma| = s-\sigma$ .

Since  $G$  is symmetric in  $s$  and  $\sigma$ , this will prove (3.2) completely. By using the elementary formula

$$(3.4) \quad \begin{aligned} 4 \sin(av s) \sin(av \sigma) = & e^{iav(s-\sigma)} - e^{iav(s+\sigma)} \\ & + e^{-iav(s-\sigma)} - e^{-iav(s+\sigma)}, \end{aligned}$$

we can split the integral in (3.1) into the two parts:

$$(3.5) \quad G_+ = \int_0^{\infty} \left( \sqrt{v^2 - 1} - v \right) \left\{ e^{iav(s-\sigma)} - e^{iav(s+\sigma)} \right\} \frac{dv}{v}$$

and

$$(3.6) \quad G_- = \int_0^{\infty} \left( \sqrt{v^2 - 1} - v \right) \left\{ e^{-iav(s-\sigma)} - e^{-iav(s+\sigma)} \right\} \frac{dv}{v}.$$

By deforming the paths of integration in the complex  $v$ -plane, we can write (see Fig. 1):

$$(3.7) \quad G_+ = \int_0^{(1+)} + \int_0^{i\infty}, \quad G_- = \int_0^{-i\infty}.$$

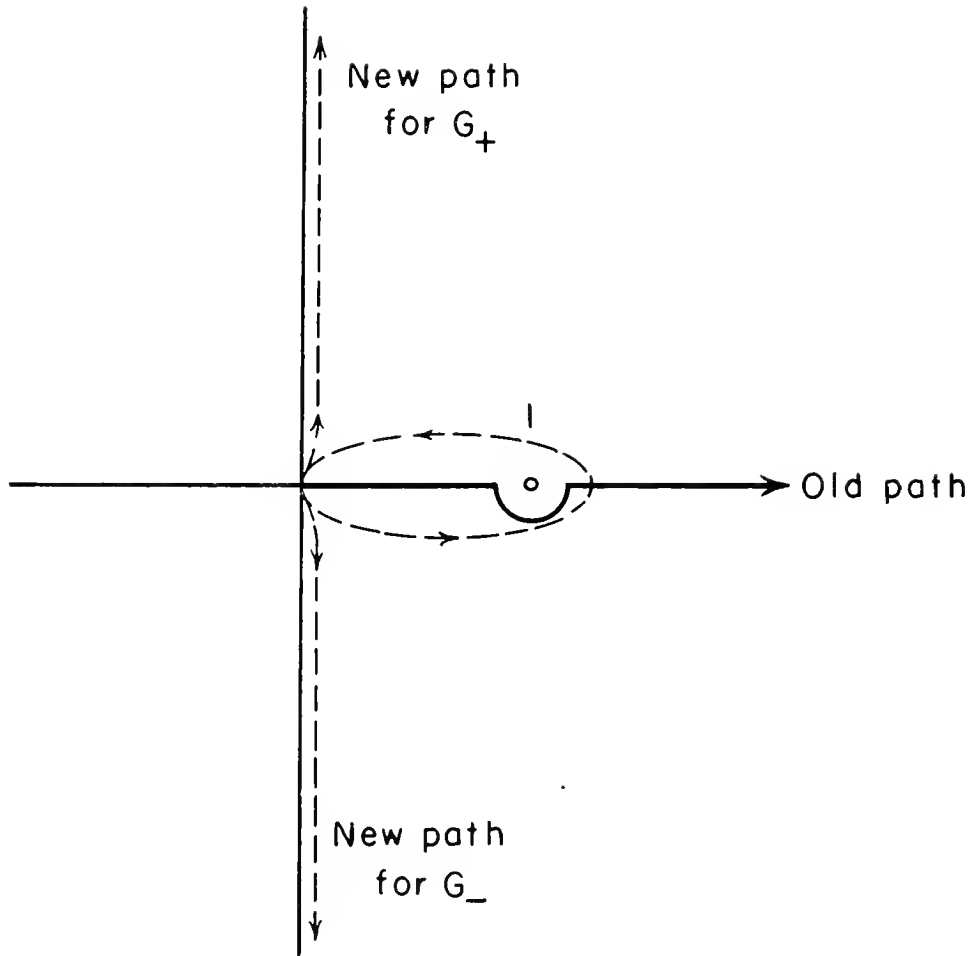


Figure 1

If we take into account that  $\sqrt{v^2-1} = -i\sqrt{1-v^2}$  for  $0 \leq v < 1$  on the old path of integration, we can derive (3.2) from (3.7) by a straightforward computation.

In order to derive (3.3), we observe that (3.2) can be written in the form

$$(3.8) \quad G(s, \sigma; a) = -\frac{a}{2} \int_0^1 \sqrt{1-w^2} \left\{ \int_{|s-\sigma|}^{s+\sigma} e^{iawt} dt \right\} dw.$$

By exchanging the order of integration in (3.8) and using the integral representations (see Erdélyi [6], pp. 14, 37)

$$(3.9) \quad \tau^{-1} J_1(a\tau) = \frac{2a}{\pi} \int_0^1 \cos(a\tau w) \sqrt{1-w^2} dw$$

$$(3.10) \quad \tau^{-1} H_1(a\tau) = \frac{2a}{\pi} \int_0^1 \sin(a\tau w) \sqrt{1-w^2} dw$$

we find that Eq. (3.3) follows immediately from (3.2).

We shall mention here a result which describes the behavior of  $G$  for  $a \rightarrow \infty$  and which is important in connection with the asymptotic behavior of the field in the aperture for large values of  $a$ . We have:

$$(3.11) \quad \lim_{a \rightarrow \infty} G(s, \sigma, a) = -\frac{i}{2} \log \left| \frac{s+\sigma}{s-\sigma} \right|.$$

The proof will not be given here.

#### 4. Existence of the solution

In this section, the following result will be proved:

Theorem I. The Fredholm integral equation

$$(4.1) \quad T(s) = S(s) + \frac{2a}{\pi} \int_0^1 G(s, \sigma; a) S(\sigma) d\sigma$$

has exactly one continuous solution  $S(\sigma)$  if  $T(s)$  satisfies (2.7) and if one of the following conditions is satisfied:

- (i)  $a$  is real
- (ii)  $a$  is purely imaginary
- (iii)  $|a|$  is sufficiently small.

For the proof of Theorem I we shall use the representation (3.2) of the kernel  $G$ . For the case where (iii) is satisfied, Theorem I has been proved elsewhere [3]. In fact, Eq. (4.1) is equivalent to the infinite system

of linear equations treated in [3], whose solution was shown to be an analytic function of  $\alpha$  for sufficiently small values of  $|\alpha|$ .

In order to prove Theorem I for the case where (i) is satisfied, we may proceed as follows:

Eq. (4.1) is a Fredholm integral equation with a continuous kernel (according to (3.2)). It is known (see [7]) to have a uniquely determined continuous solution  $S(\sigma)$  for any  $T(s)$ , provided that the homogeneous equation

$$(4.2) \quad S(s) + \frac{2\alpha}{\pi} \int_0^1 G(s, \sigma; \alpha) S(\sigma) d\sigma = 0$$

does not have a continuous solution different from zero. Now let  $\alpha$  be real, and put

$$(4.3) \quad S(s) = u(s) + i v(s),$$

$$(4.4) \quad \frac{2\alpha}{\pi} G(s, \sigma; \alpha) = K(s, \sigma) + i L(s, \sigma),$$

where  $u, v, K, L$  are real-valued functions. Then, by splitting (4.2) into its real and imaginary parts, we find

$$(4.5) \quad \int_0^1 [K(s, \sigma) u(\sigma) - L(s, \sigma) v(\sigma)] d\sigma + u(s) = 0,$$

$$(4.6) \quad \int_0^1 [K(s, \sigma) v(\sigma) + L(s, \sigma) u(\sigma)] d\sigma + v(s) = 0.$$

If we multiply Eq. (4.5) by  $-v(s)$  and Eq. (4.6) by  $u(s)$  we find, after adding the resulting equations and integrating with respect to  $s$ :

$$(4.7) \quad \int_0^1 \int_0^1 [v(s) L(s, \sigma) v(\sigma) + u(s) L(s, \sigma) u(\sigma)] ds d\sigma = 0.$$



If we can show that  $L(s, \sigma)$  is a negative definite kernel for  $\alpha > 0$ , that is, if

$$(4.8) \quad \int_0^1 \int_0^1 v(s) L(s, \sigma) v(\sigma) ds d\sigma < 0$$

whenever the continuous function  $v(s)$  does not vanish identically, then we know that (4.7) can be satisfied only if  $u(s) = v(s) = S(s) \equiv 0$ . Therefore, Part (i) of Theorem I would be proved if (4.8) were proved. Now we have from (3.2)

$$(4.9) \quad L(s, \sigma) = \frac{\alpha}{\pi} \int_0^1 \left[ \cos [\alpha w(s+\sigma)] - \cos [\alpha w(s-\sigma)] \right] \sqrt{1-w^2} \frac{dw}{w} \\ = - \frac{2\alpha}{\pi} \int_0^1 \sin(\alpha ws) \sin(\alpha w\sigma) \sqrt{1-w^2} \frac{dw}{w},$$

and therefore the left-hand side of (4.8) can be written as

$$(4.10) \quad - \frac{2\alpha}{\pi} \int_0^1 \int_0^1 \int_0^1 \sin(\alpha ws) \sin(\alpha w\sigma) v(s) v(\sigma) \sqrt{1-w^2} ds d\sigma \frac{dw}{w} \\ = - \frac{2\alpha}{\pi} \int_0^1 \left\{ \int_0^1 \sin(\alpha ws) v(s) ds \right\}^2 \sqrt{1-w^2} \frac{dw}{w}.$$

The integrand in the right-hand side of (4.10) is non-negative, and therefore the integral with respect to  $w$  can vanish only if

$$(4.11) \quad \int_0^1 \sin(\alpha ws) v(s) ds = 0$$

for  $0 \leq w \leq 1$ . Now the left-hand side of (4.11) is an analytic function of  $w$ . Expanding it into a power series in  $w$ , and observing that all the coefficients of this series must vanish, we find that

$$(4.12) \quad \alpha^n \int_0^1 s^n v(s) ds = 0, \quad (n = 0, 1, 2, \dots) .$$

If  $\alpha > 0$ , it follows from (4.12) that  $v(s) \equiv 0$  if  $v(s)$  is continuous. If  $\alpha = 0$ , then  $S = u + iv$  vanishes identically because of (4.2). If  $\alpha < 0$ , then  $L$  becomes positive definite, and (4.11) is true again. This completes the proof of assertion (i) of Theorem I.

To prove assertion (ii) of Theorem I we put  $\alpha = i\beta$ , where  $\beta$  is real.

In this case, (4.2) becomes

$$(4.13) \quad S(s) + \frac{\beta}{\pi} \int_0^1 Q(s, \sigma; \beta) S(\sigma) d\sigma = 0,$$

where, according to (3.2):

$$(4.14) \quad Q(s, \sigma; \beta) = \int_0^1 \sqrt{1-w^2} \left[ e^{-\beta w|s-\sigma|} - e^{-\beta w(s+\sigma)} \right] \frac{dw}{w} .$$

Obviously, (4.13) cannot have a non-trivial continuous solution  $S(\sigma)$  if

$Q(s, \sigma; \beta)$  is a positive kernel for  $\beta > 0$  and a negative kernel for  $\beta < 0$ .

It may suffice to treat the case where  $\beta > 0$ . Let

$$(4.15) \quad T(s, \rho) = \begin{cases} e^{\beta \rho w} & \text{if } s > \rho \\ 0 & \text{otherwise.} \end{cases}$$

Then we have

$$(4.16) \quad Q(s, \sigma; \beta) = \int_0^1 2\beta e^{-\beta w(s+\sigma)} \left\{ \int_0^1 T(s, \rho) T(\sigma, \rho) d\rho \right\} \sqrt{1-w^2} dw .$$

In order to compute

$$(4.17) \quad \int_0^1 \int_0^1 S(s) Q(s, \sigma; \beta) S(\sigma) ds d\sigma,$$

we shall introduce

$$(4.18) \quad \phi(\rho, w) = \int_0^1 e^{-\beta w s} T(s, \rho) S(s) ds = \int_\rho^1 e^{+\beta w(\rho-s)} S(s) ds.$$

Obviously,  $\phi(\rho, w)$  is a continuous function in  $\rho$  and  $w$  if  $S(s)$  is continuous, and  $\phi$  can vanish identically only if  $S(s)$  is identically zero. By combining (4.16) and (4.18) we find that the double integral in (4.17) can be written in the form

$$(4.19) \quad 2\beta \int_0^1 \int_0^1 [\phi(\rho, w)]^2 \sqrt{1-w^2} d\rho dw.$$

Since the expression (4.19) is positive for  $\beta > 0$  unless  $\phi$  vanishes identically, we see that (4.19) is positive unless  $S(s)$  vanishes identically, and this proves assertion (ii) of Theorem I.

## 5. Approximate solution of the set of linear equations

It was mentioned in the introduction that given an infinite set of linear equations, it is important to know whether an approximate solution can be found by solving the first  $N+1$  equations for the first  $N+1$  unknowns, i.e., by proceeding as if all of the other unknowns were zero. We shall call this procedure 'solving for the  $N+1$  first unknowns', and we shall prove that it is a legitimate method in the case of Bouwkamp's equations for all real values of the parameter  $\alpha$ . For this purpose, we shall introduce still another set of unknowns  $\sigma_n$ :

$$(5.1) \quad \sigma_n = \frac{s_n}{\sqrt{4n+3}} = (-1)^n \frac{\Gamma(n+3/2)}{n! \sqrt{4n+3}} b_n.$$

Correspondingly, instead of taking the  $t_m$  of Eqs (2.2), we introduce the

$$(5.2) \quad \tau_m = \frac{t_m}{\sqrt{4m+3}},$$

and instead of the  $g_{n,m}$  there we define another set of coefficients

$$(5.3) \quad \gamma_{n,m} = \sqrt{4n+3} \sqrt{4m+3} g_{n,m}.$$

Then we have instead of Eqs. (2.2):

$$(5.4) \quad \sum_{n=0}^{\infty} \gamma_{m,n} \sigma_n = \gamma_m.$$

According to Lemma 1, (Eq. (2.9)), we may write:

$$(5.5) \quad \gamma_{n,m} = \delta_{m,n} + \frac{2a}{\pi} K_{n,m},$$

where

$$K_{n,m} = \int_0^1 \int_0^1 G(s, \sigma, a) \sqrt{4n+3} P_{2n+1}(s) \sqrt{4m+3} P_{2m+1}(\sigma) ds d\sigma.$$

We shall use the notation

$$(5.6) \quad \phi_n(s) = \sqrt{4n+3} P_{2n+1}(s),$$

where the functions  $\phi_n(s)$  form a complete orthonormal set of functions for the interval  $0 \leq s \leq 1$ . Therefore we can write

$$(5.7) \quad G(s, \sigma, a) = \sum_{n,m=0}^{\infty} K_{n,m} \phi_n(s) \phi_m(\sigma).$$

The function  $G$  in (5.7) is approximated by

$$(5.8) \quad G_N(s, \sigma, a) = \sum_{n,m=0}^N K_{n,m} \phi_n(s) \phi_m(\sigma),$$

in the sense that

$$(5.9) \quad \lim_{N \rightarrow \infty} \int_0^1 \int_0^1 [G(s, \sigma, a) - G_N(s, \sigma, a)]^2 ds d\sigma = 0$$

for any fixed value of  $\alpha$ . Now we can formulate and prove the following result for the solution for the first  $N+1$  unknowns of the set of linear equations (5.4):

Theorem II: The determinant  $\Delta_N$  of the finite set of linear equations

$$(5.10) \quad \sum_{n=0}^N \gamma_{m,n} \sigma_n = \tau_m \quad (m = 0, 1, \dots, N)$$

does not vanish for any real value of  $\alpha$ . The unique solution

$$(5.11) \quad \sigma_n = \sigma_{n,N} \quad (n = 0, 1, \dots, N)$$

of (5.10) has the property that

$$(5.12) \quad \lim_{N \rightarrow \infty} \sigma_{n,N} = \sigma_{n,\infty}$$

exists for all  $n$  and that the  $\sigma_{n,\infty}$  satisfy the original equations (5.4).

We shall derive Theorem II from the following

Theorem III: For real values of  $\alpha$ , the integral equation

$$(5.13) \quad S_N(s) + \frac{2\alpha}{\pi} \int_0^1 G_N(s, \sigma, \alpha) S_N(\sigma) d\sigma = T_N(s)$$

has exactly one solution

$$(5.14) \quad S_N(\sigma) = \sum_{n=0}^N \sigma_{n,N} \phi_n(\sigma)$$

if

$$(5.15) \quad T_N(s) = \sum_{n=0}^N \tau_n \phi_n(s).$$

Proof: Let  $L_N(s, \sigma, \alpha)$  be the imaginary part of  $G_N(s, \sigma, \alpha)$ . If the homogeneous equation (5.13) has any solution at all it must be of the type (5.14), and we can write

$$(5.16) \quad S_N(s) = \sum_{n=0}^N (u_n + i v_n) \phi_n(\sigma) = U_N(\sigma) + i V_N(\sigma)$$

where  $u_n$ ,  $v_n$ ,  $U_N$ , and  $V_N$  are real and where

$$(5.17) \quad \int_0^1 \int_0^1 U_N(s) L_N(s, \sigma, \alpha) U_N(\sigma) ds d\sigma + \\ + \int_0^1 \int_0^1 V_N(s) L_N(s, \sigma, \alpha) V_N(\sigma) ds d\sigma = 0$$

(see Eq. (4.7)). But (5.17) cannot be satisfied unless  $u_n = v_n = 0$  for  $n = 0, 1, \dots, N$ , since

$$(5.18) \quad \int_0^1 \int_0^1 U_N(s) L_N(s, \sigma, \alpha) U_N(\sigma) ds d\sigma \\ = \int_0^1 \int_0^1 U_N(s) L(s, \sigma, \alpha) U_N(\sigma) ds d\sigma,$$

where  $L$  is the imaginary part  $G(s, \sigma, \alpha)$ . Now we know from the remarks after (4.8) that the right-hand side of (5.18) is always less than 0 for  $\alpha > 0$ , and vice versa, unless  $U_N \equiv 0$ . Therefore, (5.13) has at most one solution and it follows from Fredholm's theory that it has exactly one solution.

Now we can prove Theorem II. If we write the only solution of (5.13) in the form (5.14), the coefficients  $\sigma_{n,N}$  must satisfy Eq. (5.10). According to Theorem III, these equations cannot have more than one solution, and therefore the determinant of the system does not vanish. This proves the first part of Theorem II. The second part, namely the proof of (5.12), is somewhat tedious;

we shall outline the proof here.  $S(s)$  is the uniquely determined solution of (2.16). Then it suffices to show that

$$(5.19) \quad \lim_{N \rightarrow \infty} \int_0^1 |S(s) - S_N(s)|^2 ds = 0.$$

In fact, because of Parseval's equation, we have

$$(5.20) \quad \int_0^1 |S(s) - S_N(s)|^2 ds = \sum_{n=0}^N |\sigma_n - \sigma_{n,N}|^2 + \sum_{n=N+1}^{\infty} |\sigma_n|^2,$$

where

$$\sigma_n = \int_0^1 S(s) \phi_n(s) ds.$$

Therefore, (5.19) implies (5.12). In order to prove (5.19), we may proceed as follows. By subtracting (5.13) from (2.16) we find

$$(5.21) \quad \begin{aligned} S(s) - S_N(s) + \frac{2a}{\pi} \int_0^1 G(s, \sigma) [S(\sigma) - S_N(\sigma)] d\sigma \\ = T(s) - T_N(s) - \int_0^1 [G(s, \sigma) - G_N(s, \sigma)] S_N(\sigma) d\sigma. \end{aligned}$$

Now let  $R(s, \sigma)$  be the resolving kernel of (2.16). According to Theorem I, it follows from Fredholm's theory that  $R$  is a continuous function of  $s$  and  $\sigma$  such that the solution of (4.1) can be written in the form

$$(5.22) \quad S(s) = T(s) + \int_0^1 R(s, \sigma) T(\sigma) d\sigma.$$

If we look upon (5.21) as an integral equation for  $S(s) - S_N(s)$ , we obtain from an application of (5.22):

$$(5.23) \quad S(s) - S_N(s) = H_N(s) + \int_0^1 R(s, \sigma) H_N(\sigma) d\sigma,$$

where  $H_N(s)$  denotes the right-hand side of (5.21). Since as  $N \rightarrow \infty$

$$(5.24) \quad \int_0^1 |T(s) - T_N(s)|^2 ds \rightarrow 0,$$

(5.19) is true if

$$(5.25) \quad \int_0^1 \left| \int_0^1 [G(s, \sigma) - G_N(s, \sigma)] S_N(\sigma) d\sigma \right|^2 ds \\ \leq \varepsilon_N \int_0^1 |S_N(\sigma)|^2 d\sigma,$$

where  $\varepsilon_N \rightarrow 0$  as  $N \rightarrow \infty$ . In fact, it follows from (5.25) and (5.23) by a standard procedure that (5.19) holds. Since (5.25) is a consequence of (5.9) and of Schwartz's inequality, Theorem II is true.



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